

ATV71H075N4

variable speed drive ATV71 - 0.75kW 1HP - 480V



Main

Range of product	Altivar 71
Product or component type	Variable speed drive
Product specific application	Complex, high-power machines
Assembly style	With heat sink
Component name	ATV71
EMC filter	Integrated
Network number of phases	3 phases
Power supply voltage	380...480 V (- 15...10 %)
Motor power kW	0.75 kW at 380...480 V 3 phases
Motor power hp	1 hp at 380...480 V 3 phases
Line current	3 A for 480 V 3 phases 0.75 kW / 1 hp 3.7 A for 380 V 3 phases 0.75 kW / 1 hp
Apparent power	2.4 kVA at 380 V 3 phases 0.75 kW / 1 hp
Prospective line I _{sc}	≤ 5 kA , 3 phases
Nominal output current	2.1 A at 4 kHz 460 V 3 phases 0.75 kW / 1 hp 2.3 A at 4 kHz 380 V 3 phases 0.75 kW / 1 hp
Maximum transient current	3.5 A for 60 s 3 phases 0.75 kW / 1 hp 3.8 A for 2 s 3 phases 0.75 kW / 1 hp
Speed drive output frequency	0...1600 Hz
Nominal switching frequency	4 kHz
Switching frequency	1...16 kHz adjustable 4...16 kHz with derating factor
Asynchronous motor control profile	ENA (Energy adaptation) system for unbalanced loads Flux vector control (FVC) with sensor (current vector) Sensorless flux vector control (SFVC) (voltage or current vector) Voltage/Frequency ratio (2 or 5 points)
Type of polarization	No impedance for Modbus

Complementary

Product destination	Asynchronous motors Synchronous motors
Power supply voltage limits	323...528 V
Power supply frequency	50...60 Hz (- 5...5 %)
Power supply frequency limits	47.5...63 Hz
Speed range	1...100 for asynchronous motor in open-loop mode, without speed feedback 1...1000 for asynchronous motor in closed-loop mode with encoder feedback 1...50 for synchronous motor in open-loop mode, without speed feedback
Speed accuracy	+/- 0.01 % of nominal speed for 0.2 T _n to T _n torque variation in closed-loop mode with encoder feedback +/- 10 % of nominal slip for 0.2 T _n to T _n torque variation without speed feedback
Torque accuracy	+/- 15 % in open-loop mode, without speed feedback +/- 5 % in closed-loop mode with encoder feedback
Transient overtorque	170 % of nominal motor torque +/- 10 % for 60 s 220 % of nominal motor torque +/- 10 % for 2 s
Braking torque	30 % without braking resistor < 150 % with braking or hoist resistor

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Synchronous motor control profile	Vector control without speed feedback
Regulation loop	Adjustable PI regulator
Motor slip compensation	Adjustable Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points) Suppressable
Diagnostic	1 LED red presence of drive voltage
Output voltage	<= power supply voltage
Insulation	Electrical between power and control
Type of cable for mounting in an enclosure	With a NEMA Type1 kit: 3-strand UL 508 cable at 40 °C, copper 75 °C PVC With an IP21 or an IP31 kit: 3-strand IEC cable at 40 °C, copper 70 °C PVC Without mounting kit: 1-strand IEC cable at 45 °C, copper 70 °C PVC Without mounting kit: 1-strand IEC cable at 45 °C, copper 90 °C XLPE/EPR
Electrical connection	AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1...LI6, PWR terminal 2.5 mm ² / AWG 14 L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB terminal 4 mm ² / AWG 10
Tightening torque	AI1-/AI1+, AI2, AO1, R1A, R1B, R1C, R2A, R2B, LI1...LI6, PWR 0.6 N.m L1/R, L2/S, L3/T, U/T1, V/T2, W/T3, PC/-, PO, PA/+, PA, PB 1.4 N.m / 12.3 lb.in
Supply	Internal supply , 24 V DC , voltage limits 21...27 V , ≤ 200 mA for overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm) , 10.5 V DC +/- 5 % , ≤ 10 mA for overload and short-circuit protection
Analogue input number	2
Analogue input type	AI1-/AI1+ bipolar differential voltage +/- 10 V DC , input voltage 24 V max , resolution 11 bits + sign AI2 software-configurable current 0...20 mA , impedance 242 Ohm , resolution 11 bits AI2 software-configurable voltage 0...10 V DC , input voltage 24 V max , impedance 30000 Ohm , resolution 11 bits
Input sampling time	AI1-/AI1+ 2 ms , +/- 0.5 ms for analog input(s) AI2 2 ms , +/- 0.5 ms for analog input(s) LI1...LI5 2 ms , +/- 0.5 ms for discrete input(s) LI6 (if configured as logic input) 2 ms , +/- 0.5 ms for discrete input(s)
Response time	AO1 2 ms , tolerance +/- 0.5 ms for analog output(s) R1A, R1B, R1C 7 ms , tolerance +/- 0.5 ms for discrete output(s) R2A, R2B 7 ms , tolerance +/- 0.5 ms for discrete output(s) <= 100 ms in STO (Safe Torque Off)
Absolute accuracy precision	AI1-/AI1+ +/- 0.6 % for a temperature variation 60 °C AI2 +/- 0.6 % for a temperature variation 60 °C AO1 +/- 1 % for a temperature variation 60 °C
Linearity error	AI1-/AI1+, AI2 +/- 0.15 % of maximum value AO1 +/- 0.2 %
Analogue output number	1
Analogue output type	AO1 software-configurable voltage 0...10 V DC , impedance 470 Ohm , resolution 10 bits AO1 software-configurable current 0...20 mA , impedance 500 Ohm , resolution 10 bits AO1 software-configurable logic output 10 V ≤ 20 mA
Discrete output number	2
Discrete output type	R1A, R1B, R1C configurable relay logic NO/NC , electrical durability 100000 cycles R2A, R2B configurable relay logic NO , electrical durability 100000 cycles
Minimum switching current	Configurable relay logic 3 mA at 24 V DC
Maximum switching current	R1, R2 on resistive load, 5 A at 250 V AC, cos phi = 1, R1, R2 on resistive load, 5 A at 30 V DC, cos phi = 1, R1, R2 on inductive load, 2 A at 250 V AC, cos phi = 0.4, R1, R2 on inductive load, 2 A at 30 V DC, cos phi = 0.4,
Discrete input number	7
Discrete input type	LI1...LI5 programmable 24 V DC , with level 1 PLC , impedance 3500 Ohm LI6 switch-configurable 24 V DC , with level 1 PLC , impedance 3500 Ohm LI6 switch-configurable PTC probe 0...6 , impedance 1500 Ohm PWR safety input 24 V DC , impedance 1500 Ohm
Discrete input logic	LI1...LI5 negative logic (sink) , > 16 V (state 0) , < 10 V (state 0) LI1...LI5 positive logic (source) , < 5 V (state 0) , > 11 V (state 0) LI6 (if configured as logic input) negative logic (sink) , > 16 V (state 0) , < 10 V (state 0) LI6 (if configured as logic input) positive logic (source) , < 5 V (state 0) , > 11 V (state 0) PWR , < 2 V (state 0) , > 17 V (state 0)

Acceleration and deceleration ramps	S, U or customized Automatic adaptation of ramp if braking capacity exceeded, by using resistor Linear adjustable separately from 0.01 to 9000 s
Braking to standstill	By DC injection
Protection type	Drive overheating protection Drive thermal protection Drive short-circuit between motor phases Drive input phase breaks Drive overcurrent between output phases and earth Drive overvoltages on the DC bus Drive break on the control circuit Drive against exceeding limit speed Drive line supply undervoltage Drive line supply overvoltage Drive against input phase loss Motor thermal protection Motor motor phase break Motor power removal
Insulation resistance	> 1 MOhm at 500 V DC for 1 minute to earth
Frequency resolution	Analog input 0.024/50 Hz Display unit 0.1 Hz
Communication port protocol	CANopen Modbus
Type of connector	1 RJ45 for Modbus on front face 1 RJ45 for Modbus on terminal Male SUB-D 9 on RJ45 for CANopen
Physical interface	2-wire RS 485 for Modbus
Transmission frame	RTU for Modbus
Transmission rate	20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 9600 bps, 19200 bps for Modbus on front face
Data format	8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal
Number of addresses	1...127 for CANopen 1...247 for Modbus
Method of access	Slave for CANopen
Marking	CE
Operating position	Vertical +/- 10 degree
Product weight	3 kg
Option card	CC-Link communication card DeviceNet communication card Ethernet/IP communication card Fipio communication card Interbus-S communication card Modbus/Uni-Telway communication card Modbus Plus communication card Modbus TCP communication card Profibus DP communication card Profibus DP V1 communication card Interface card for encoder I/O extension card Controller inside programmable card Overhead crane card

Environment

Noise level	43 dB conforming to 86/188/EEC
Dielectric strength	3535 V DC between earth and power terminals 5092 V DC between control and power terminals
Electromagnetic compatibility	1.2/50 μ s - 8/20 μ s surge immunity test conforming to IEC 61000-4-5 level 3 Conducted radio-frequency immunity test conforming to IEC 61000-4-6 level 3 Electrical fast transient/burst immunity test conforming to IEC 61000-4-4 level 4 Electrostatic discharge immunity test conforming to IEC 61000-4-2 level 3 Radiated radio-frequency electromagnetic field immunity test conforming to IEC 61000-4-3 level 3 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Standards	EN/IEC 61800-3 EN/IEC 61800-5-1 EN 55011 class A group 1 EN 61800-3 environments 1 category C2 EN 61800-3 environments 2 category C2 IEC 60721-3-3 class 3C1 IEC 60721-3-3 class 3S2 UL Type 1
Product certifications	C-Tick CSA GOST NOM 117 UL
Pollution degree	2 conforming to EN/IEC 61800-5-1
IP degree of protection	IP20 on upper part without blanking plate on cover conforming to EN/IEC 61800-5-1 IP20 on upper part without blanking plate on cover conforming to EN/IEC 60529 IP21 conforming to EN/IEC 61800-5-1 IP21 conforming to EN/IEC 60529 IP41 on upper part conforming to EN/IEC 61800-5-1 IP41 on upper part conforming to EN/IEC 60529 IP54 on lower part conforming to EN/IEC 61800-5-1 IP54 on lower part conforming to EN/IEC 60529
Vibration resistance	1 gn (f = 13...200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 3...13 Hz) conforming to EN/IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60068-2-27
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3 5...95 % without dripping water conforming to IEC 60068-2-3
Ambient air temperature for operation	-10...50 °C without derating
Ambient air temperature for storage	-25...70 °C
Operating altitude	1000...3000 m with current derating 1 % per 100 m \leq 1000 m without derating
RoHS EUR conformity date	4Q2009
RoHS EUR status	Will be compliant